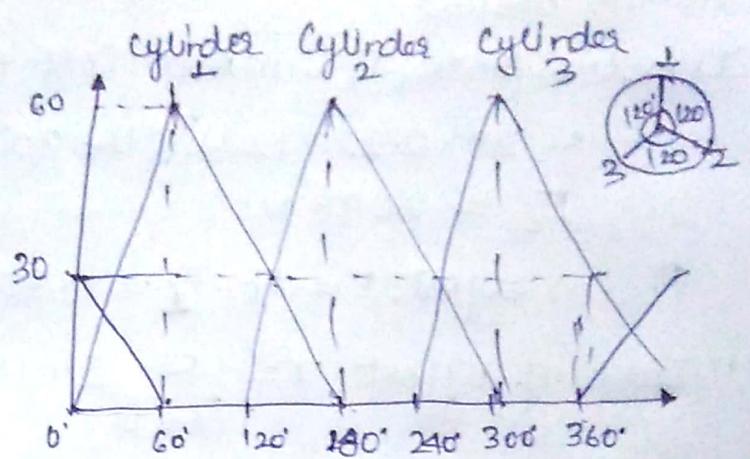


Ans. 2:-

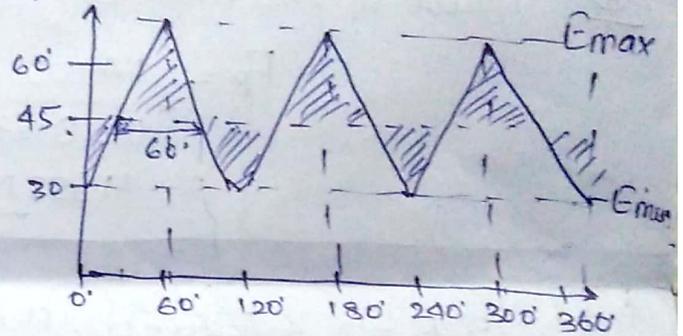
(i) Work done/cycle
 = Area of three Δ
 = $3 \times \frac{1}{2} \times \pi \times 60 = 90\pi$

Mean Torque = T_m
 $T_m = \frac{\text{Work done/cycle}}{\text{Angle turned}}$
 $T_m = \frac{90\pi}{2\pi} = 45 \text{ N.m}$

$P = T_m \omega = \frac{45 \times 2 \times \pi \times 400}{15 \times 60 \times 30} = 1885 \text{ W.}$



(ii) $\Delta E = I \omega^2 K$
 $\Delta E = E_{\text{max}} - E_{\text{mean}} =$
 $\frac{1}{2} \times \frac{60 \times \pi}{180} \times (60 - 45)$
 $= \frac{1}{2} \times \frac{\pi}{2} \times 15^2 = 2.5\pi \text{ N.m.}$



$2.5\pi \text{ N.m} = mK^2 \omega^2 K$

$K = \frac{2.5 \times \pi}{10 \times (0.088)^2 \times \left(\frac{2\pi \times 400}{60}\right)^2} = 0.0578 \text{ or } 5.78\%$

Ans. 3:- radius, $r = \frac{440}{2} = 220 \text{ mm.}$

Length of Connecting Rod = 924 mm.

$\eta = \frac{l}{r} = \frac{924}{220} = 4.2$

$N = 210 \text{ rpm, } \omega = \frac{2\pi N}{60}$

$\omega = \frac{2\pi \times 210}{60} = 22 \text{ rad/s.}$

$\sin \beta = \frac{\sin \theta}{\eta} = \frac{\sin 30^\circ}{4.2} = 0.119$

$\beta = \sin^{-1}(0.119) = 6.837^\circ$

$F_p = (P_1 A_1 - P_2 A_2)$
 $= \left\{ 500 \times 10^3 \times \frac{\pi}{4} \times 0.22^2 - 60 \times 10^3 \times \frac{\pi}{4} (0.22^2 - 0.04^2) \right\}$
 $F_p = 19007 - 2206$
 $= 16801 \text{ N.}$

P.T.O

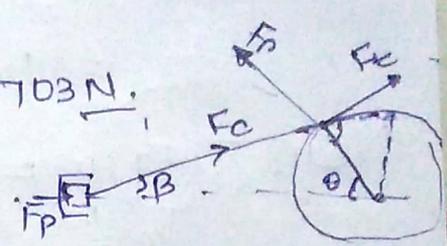
Continue Ans (3)

Inertia force, $F_i = m \cdot \omega^2 \left(\cos \theta + \frac{\cos 2\theta}{n} \right)$

$$F_i = 20 \times 0.22 \times (122)^2 \left(\cos 30^\circ + \frac{\cos 60^\circ}{4.2} \right)$$

$$F_i = 2098 \text{ N}$$

Piston effort, $F = F_p - F_i = 16801 - 2098 = 14703 \text{ N}$



(ii) Turning Effort, $T = \frac{F}{\cos \beta} \sin(\theta + \beta) \times r$

$$T = \frac{14703}{\cos 6.837^\circ} \sin(30^\circ + 6.837^\circ) \times 0.22$$

$$= 1953 \text{ N.m}$$

(iii) Thrust on the bearings, $F_p = \frac{F}{\cos \beta} \cos(\theta + \beta)$

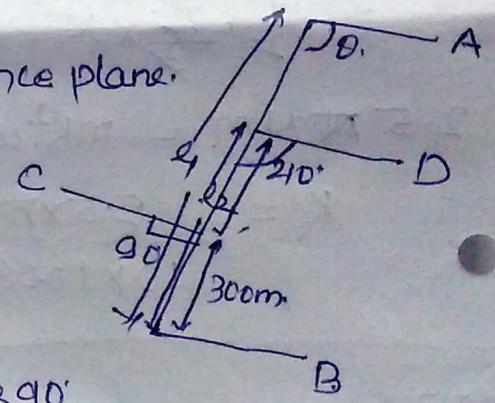
$$F_p = \frac{14703}{\cos 6.837^\circ} \times \cos(30^\circ + 6.837^\circ)$$

$$= 11852 \text{ N}$$

Ans 4 $\sum F_x = 0$ & $\sum F_y = 0$, Plane B is reference plane.

$$m_A P_A \sin \theta_A + m_B P_B \sin \theta_B + m_C P_C \sin \theta_C + m_D P_D \sin \theta_D = 0$$

$$m(0.360) \sin \theta + 15(0.48) \sin 10^\circ + 25(0.240) \sin 90^\circ + 20(0.300) \sin 210^\circ = 0 \quad \text{--- (i)}$$



Similarly, $\sum F_y = 0$,

$$m(0.360) \cos \theta + 15(0.48) \cos 10^\circ + 25(0.240) \cos 90^\circ + 20(0.300) \cos 210^\circ = 0 \quad \text{--- (ii)}$$

θ & m are unknown, Two unknown & two equation, from solving (i) & (ii) we get $m = 10.02 \text{ kg}$ & $\theta = 236.26$

Take Moment about B, $\sum M_x = 0$ & $\sum M_y = 0$, $M_x = m p l \sin \theta$, $M_y = m p l \cos \theta$

$$10 \times (0.360) l_1 \cos(236) + 15(0.48) \cos(10^\circ) \times 10 + 25(0.240) \times (0.3) \cos 90^\circ + 20(0.300) l_2 \cos 210^\circ = 0 \quad \text{--- (iii)}$$

$$10 \times (0.360) l_1 \sin(236) + 15(0.48) \sin(10^\circ) \times 10 + 25(0.240) \times 0.3 \sin 90^\circ + 20(0.3) \sin 210^\circ \times l_2 = 0 \quad \text{--- (iv)}$$

continue ans (4).

$$-2.984 l_1 + 1.8 - 3l_2 = 0 \quad \text{--- (iv)}$$

$$-2.01 l_1 - 3\sqrt{3} l_2 = 0 \quad \text{--- (v)}$$

Solve (iv) & (v), and get value of l_1 & l_2 .

$$l_1 = 989 \text{ mm towards right}$$

$$l_2 = 382.6 \text{ mm towards left}$$

Ans. 5 $f = \frac{\omega}{2\pi}$, $\omega = 2\pi f$

$$\omega = \sqrt{\frac{k}{m}}$$

$$2\pi \times 3.56 = \sqrt{\frac{k_0}{m_0}} \quad \text{--- (i)}$$

$$2\pi \times 2.9 = \sqrt{\frac{k_0}{m_0 + 5}} \quad \text{--- (ii)}$$

divide (i) by (ii).

$$\frac{2\pi \times 3.56}{2\pi \times 2.9} = \sqrt{\frac{k_0}{m_0}} \times \sqrt{\frac{m_0 + 5}{k_0}}$$

Square on both sides

$$\left(\frac{3.56}{2.9}\right)^2 = \frac{m_0 + 5}{m_0} = 1 + \frac{5}{m_0}$$

$$1.507 = 1 + \frac{5}{m_0} \quad \therefore m_0 = 9.86 \text{ kg} \approx 10 \text{ kg}$$

Put the value of m_0 in eqn (i) & solve for k_0

$$k_0 = 4.98 \text{ kN/m} \approx 5 \text{ N/mm}$$

Ans 1

1.1 - d

1.2 - a

1.3 - d

1.4 - a

1.5 - a

Ans 6:-

$$m\ddot{x} + c\dot{x} + kx = 0$$

$$\ddot{x} + \frac{c}{m}\dot{x} + \frac{k}{m}x = 0$$

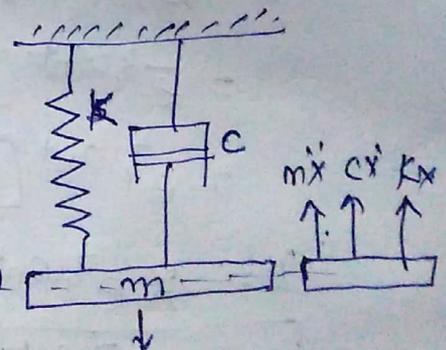
$$g. \frac{d^2x}{dt^2} + \frac{c}{m}\frac{dx}{dt} + \frac{k}{m}x = 0 \quad \text{--- (1)}$$

It is 2nd order differential equation, its solⁿ

will be $x = Ae^{\alpha_1 t} + Be^{\alpha_2 t}$

A.E of eqn (1), $D^2 + \frac{c}{m}D + \frac{k}{m} = 0$

roots are α_1, α_2
 $\alpha_{1,2} = -\frac{c}{2m} \pm \sqrt{\left(\frac{c}{2m}\right)^2 - \left(\frac{k}{m}\right)}$



Put $\sqrt{\frac{(\frac{c}{2m})^2}{\frac{s}{m}}} = \zeta$ (damping factor or ratio)

$$\frac{c}{2m\omega_n} = \zeta, \quad \frac{c}{2m} = \zeta \cdot \omega_n.$$

$$\frac{\frac{c}{2m}}{\sqrt{\frac{s}{m}}} = \zeta$$

$$\alpha_{1,2} = -\left(\frac{c}{2m}\right) \pm \sqrt{\left(\frac{c}{2m}\right)^2 - \left(\frac{s}{m}\right)^2}$$

$$= -\zeta \cdot \omega_n \pm \sqrt{\zeta^2 \omega_n^2 - \omega_n^2}$$

$$\alpha_{1,2} = (-\zeta \pm \sqrt{\zeta^2 - 1}) \cdot \omega_n.$$

Now if $\zeta < 1$, the system is underdamped then

$$\alpha_{1,2} = [-\zeta \pm i\sqrt{1-\zeta^2}] \omega_n.$$

$$x = A e^{-\zeta \omega_n t} [A e^{i\sqrt{1-\zeta^2} \omega_n t} + B e^{-i\sqrt{1-\zeta^2} \omega_n t}]$$

Put $\sqrt{1-\zeta^2} \cdot \omega_n = \omega_d$

$$x = e^{-\zeta \omega_n t} [A e^{i\omega_d t} + B e^{-i\omega_d t}]$$

$$\dot{x} = e^{-\zeta \omega_n t} [A(\cos \omega_d t + i \sin \omega_d t) + B(\cos \omega_d t - i \sin \omega_d t)]$$

$$= e^{-\zeta \omega_n t} [(A+B) \cos \omega_d t + i \sin \omega_d t (A-B)]$$

$$= e^{-\zeta \omega_n t} [C \cos \omega_d t + D \sin \omega_d t]$$

$$\begin{aligned} A+B &= X \sin \phi = C \\ i(A-B) &= X \cos \phi = D \end{aligned}$$

$$x = X e^{-\zeta \omega_n t} [\sin \phi \cos \omega_d t + \cos \phi \sin \omega_d t]$$

$$x = X e^{-\zeta \omega_n t} \sin(\omega_d t + \phi)$$